

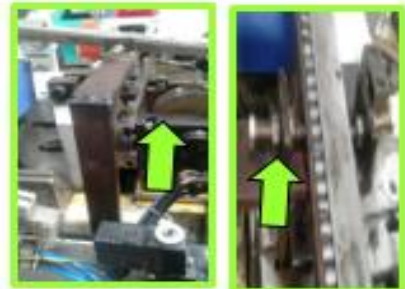
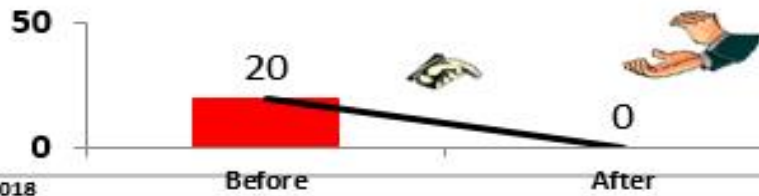


Success Celebration : May-18
Employee Present for Success celebration

		TPM CIRCLE NO :-	1	ACTIVITY		KK	QM	PM	JH	SHE	OTPM	DM	E & T	KAIZEN IDEA SHEET											
		TPM CIRCLE NAME :		LOSS NO./STEP																					
Plant : P14		DEPT :	Production	RESULT AREA		C	Q	P	P, C	S	M, D	P, C	M												
CELL :	Thread Rolling	CELL NAME :	Thread Rolling		M/C STAGE:	MTR 15E			OPERATION:			Thread rolling													
KAIZEN THEME :		KAIZEN IDEA :																							
To reduce speed loss during threading automation time.		Rigid base & clamping to screw feeder.							BENCHMARK:		20 min														
									TARGET:		0 min														
									KAIZEN START:		01.05.2018														
PROBLEM PRESENT STATUS :		COUNTERMEASURE:							TARGET DATE:		20.05.2018														
20 min speed loss getting in every shift during screw automation.		Provided a angular rigid base & both side bolt clamping to feeder , where feeder will not get disturbed during automation time.							KAIZEN FINISH:		20.05.2018														
									TEAM MEMBERS:																
									Mr. Manas Dey																
									Mr. Murali MN																
									BENEFITS:-		Operator moral increased & user friendly.														
WHY-WHY ANALYSIS:		BEFORE			AFTER			KAIZEN SUSTAINANCE																	
<p>Why1:- 20 min speed loss getting in every shift during screw automation.</p> <p>Why2:- Feeder adjustment done frequently.</p> <p>Why3:- Feeder getting disturbed during bowl feeder vibrating time.</p> <p>Why4:- No rigid base & clamping to screw feeder.</p>								<p>WHAT TO DO: Ir reversible Kaizen</p> <p>HOW TO DO: ----</p> <p>FREQUENCY: One time activity.</p> <p>SCOPE & PLAN FOR HORIZONTAL DEPLOYMENT</p> <table border="1"> <thead> <tr> <th>SR. NO</th> <th>CELL/ PRODUCT</th> <th>TDC</th> <th>RESP.</th> <th>STATUS</th> </tr> </thead> <tbody> <tr> <td>-</td> <td>----</td> <td>----</td> <td>----</td> <td>----</td> </tr> </tbody> </table>								SR. NO	CELL/ PRODUCT	TDC	RESP.	STATUS	-	----	----	----	----
SR. NO	CELL/ PRODUCT	TDC	RESP.	STATUS																					
-	----	----	----	----																					
ROOT CAUSE		RESULTS:																							
No rigid base & clamping to screw feeder.		Speed loss reduced from 20 min to zero.																							
REGISTRATION NO.:																									
DATE:																									
REGISTERED BY:																									
MANAGER SIGN: Mr. Manas Kumar Dey																									
																									
		<p>HD SCOPE INFORMATION IN OTHER PLANT</p> <table border="1"> <thead> <tr> <th>SR.NO.</th> <th>PLANT</th> <th>WHEN</th> <th>WHOM</th> <th>STATUS</th> </tr> </thead> <tbody> <tr> <td>---</td> <td>----</td> <td>----</td> <td>----</td> <td>----</td> </tr> </tbody> </table>													SR.NO.	PLANT	WHEN	WHOM	STATUS	---	----	----	----	----	
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